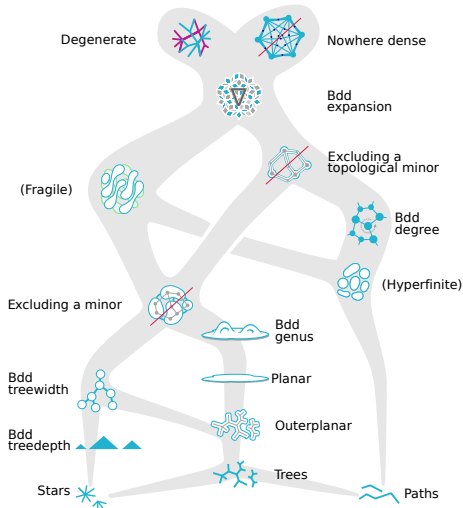


Graph structure useful for approximation problems

Marcin Wrochna, University of Oxford



Based on work with Miguel Romero, Standa Živný. Figure based on Felix Reidl's.

Question

Approximation* is easy on planar graphs
and hard on some bounded degree graphs.

Where is the boundary?

What makes planar graphs easy and other graph classes hard?

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= $(1 \pm \epsilon)$ approximation in polynomial time, $n^{f(\epsilon)}$.
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We need (much) more expressive problems.

Constraint Satisfaction Problems (CSPs)

You probably know some of:

Max-2-SAT $(x \vee \neg y) \wedge (y \vee \neg z) \wedge \dots$

Max-Cut $v \mapsto$ either L or R, maximize $\#_{uv} : u \in L, v \in R$

Max-5-Coloring $v \mapsto$ color, maximize $\#_{uv} : col(u) \neq col(v)$

Constraint Satisfaction Problems (CSPs)

In general Max-2-CSP the input is:

- graph G
- alphabet Σ_v for each vertex v
- constraint C_{uv} for each edge uv

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Exact solving

Theorem (Grohe, Schwentick, Segoufin '01)

2-CSP(\mathcal{G}) is in P $\Leftrightarrow \mathcal{G}$ has bounded treewidth.

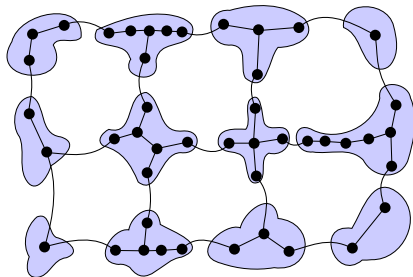
Exact solving

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Grid Minor Theorem (Robertson & Seymour '86)

G has large tw $\Leftrightarrow G$ contains a large grid as a minor



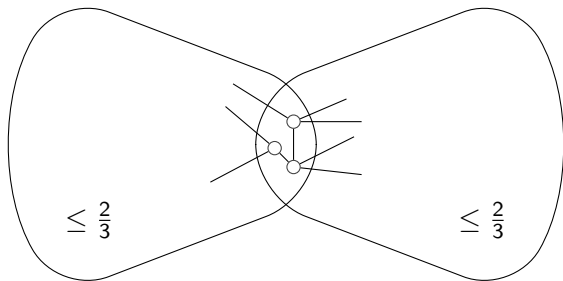
Exact solving

Theorem (Grohe, Schwentick, Segoufin '01)

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Theorem (Dvořák, Norin '18)

G has bounded treewidth iff
every subgraph has a bounded balanced separation.



Exact solving

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Theorem (Grohe '07)

$\text{Hom}(\mathcal{G}, *)$ is P $\Leftrightarrow \mathcal{G}$ has bounded treewidth up to hom. eq.
(for example, bipartite graphs are easy).

Fixed-parameter-tractability

Given G and k , decide if $\text{opt}(G) \leq k$ in time $f(k) \cdot |G|^c$.

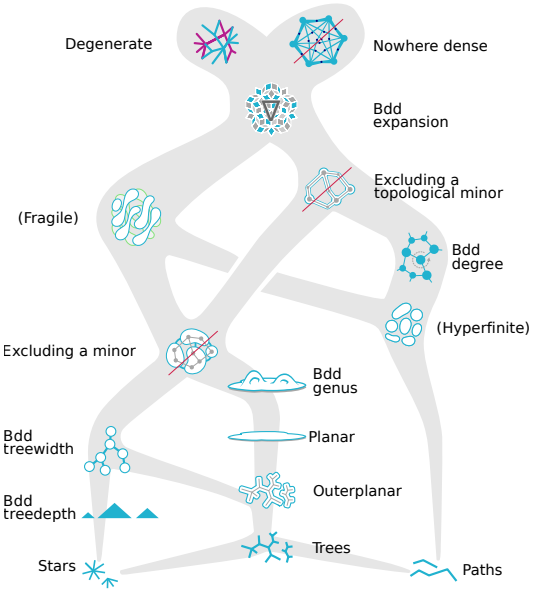
Given G and ϕ , decide $G \models \phi$ in time $f(|\phi|) \cdot |G|^c$.

For properties expressible by MSO_2 formulas,
this is possible in $\mathcal{G} \iff \mathcal{G}$ has bounded treewidth.

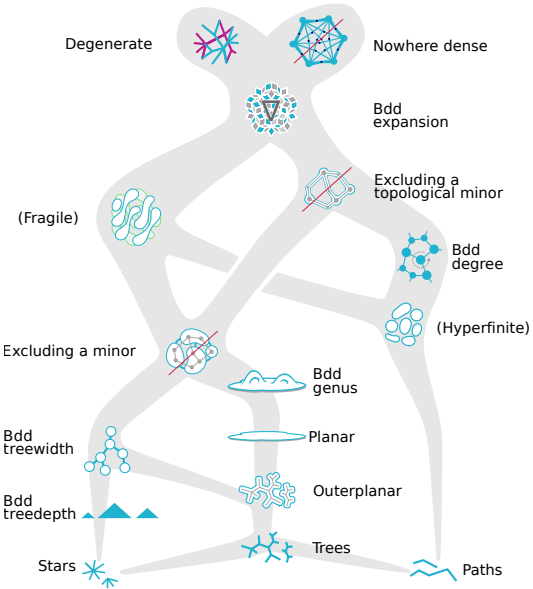
For properties expressible by FO formulas,
this is possible in $\mathcal{G} \iff \mathcal{G}$ is *nowhere-dense*.

Sparse graph theory by: Gaifman, Courcelle, Arnborg, Lagergreen, Seese, Adler, Downey, Fellows, Frick, Grohe, Flum, Nešetřil, Ossona de Mendez, Dawar, Dvořák, Král, Thomas, Kreutzer, Siebertz, ...

Notions of sparsity

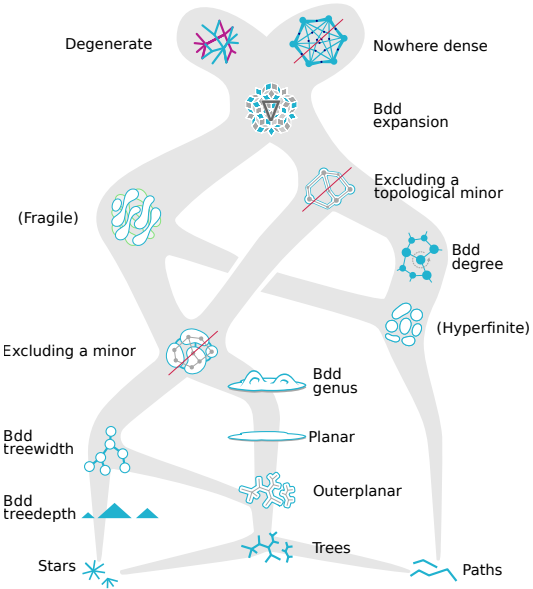


Notions of sparsity



\mathcal{G} is degenerate
 \iff
 graphs in \mathcal{G} and their subgraphs
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Notions of sparsity



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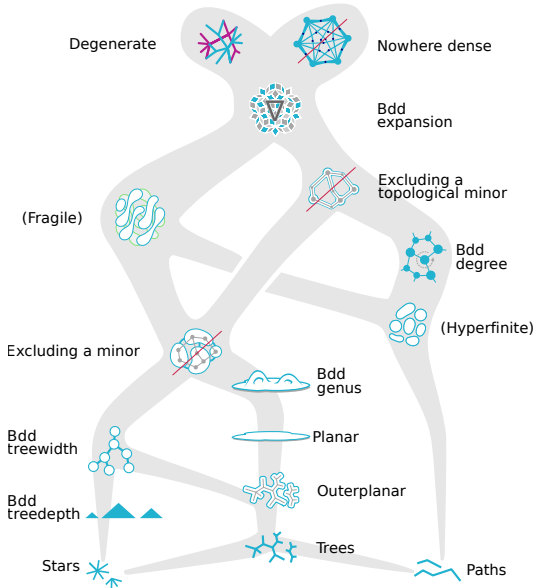
graphs in \mathcal{G} and their subgraphs
have bounded average degree



1-subdivision of any graph has
average degree ≤ 4

So $\mathcal{G} = \{1\text{-subdivisions}\}$
is degenerate, but hard.

Notions of sparsity

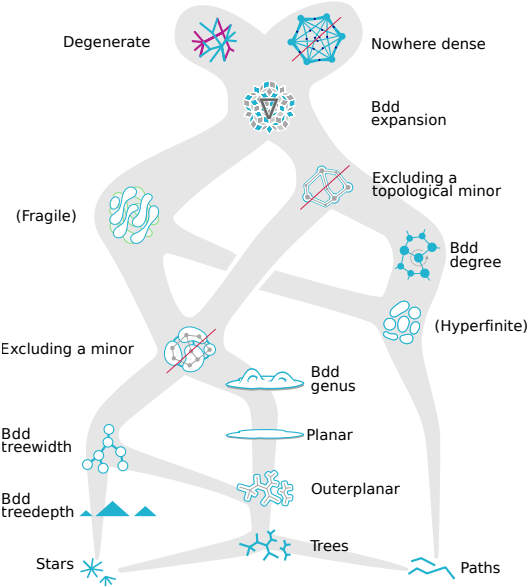


\mathcal{G} is nowhere-dense



\forall_r not all graphs have an
 $\leq r$ -subdivision in \mathcal{G}

Notions of sparsity



Conjecture
 Max-CSP(\mathcal{G}) has a PTAS
 \Updownarrow
 \mathcal{G} is fragile

Lipton-Tarjan

If graph has $o(n)$ balanced separators, divide & conquer.

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General intuition: either $o(n)$ separators or expanders?

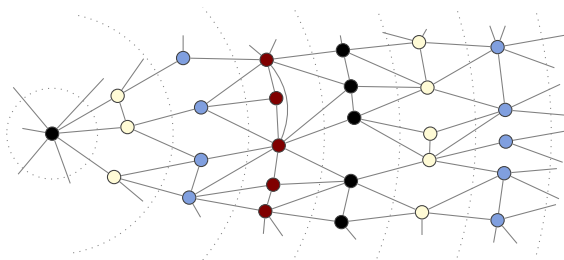
One actually needs $O(\frac{n}{\log n})$, up to $\log \log n$ factors.

(Moshkovitz, Shapira '15)

Baker's technique (FOCS'83)

In a planar graph, many problems have a PTAS as follows:

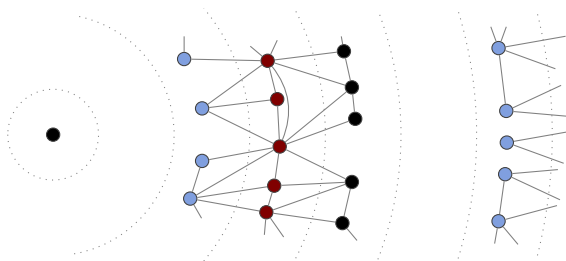
- color in layers by distance mod $\lceil \frac{1}{\varepsilon} \rceil$
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- try each color c : remove it;
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What other graph classes can be partitioned into layers of [...] bounded treewidth?

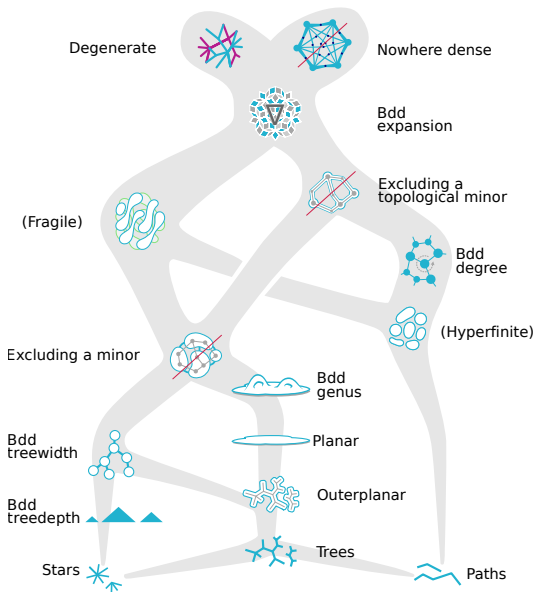
- graphs embeddable in a surface S , H -minor-free graphs
- graph embeddable in plane with $\leq c$ crossings per edge
- some geometric intersection graphs

Dvořák '16

\mathcal{G} is *fractionally-tw-fragile* if for every $\varepsilon > 0$, every $G \in \mathcal{G}$ has a **distribution of sets** $X \subseteq V(G)$ **such that:**

- removing X reduces treewidth to $\leq k(\varepsilon)$ and
 - each vertex is removed with probability $\leq \varepsilon$.
- more general: 3-dimensional grids, ...
 - simpler proofs
 - more useful than just Lipton-Tarjan
 - robust (treewidth \leftrightarrow treedepth, vertex \leftrightarrow edge, ...)

Notions of sparsity



Conjecture

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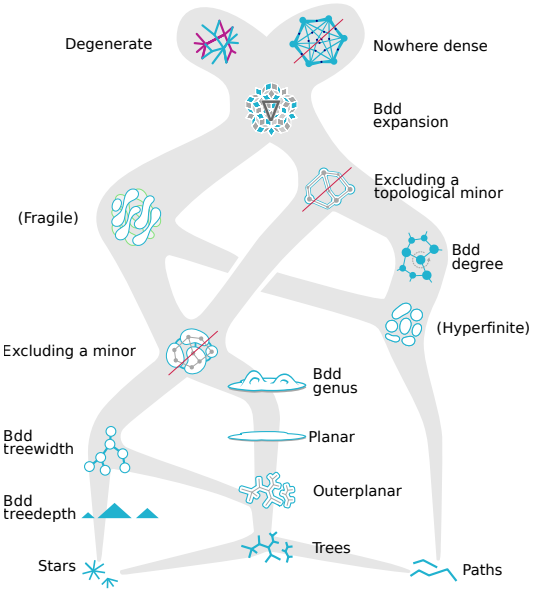
\Uparrow **Theorem** (Dvořák, RWŽ)

Algorithm: simply run
Sherali-Adams LP relaxation

\Downarrow **Questions, questions...**

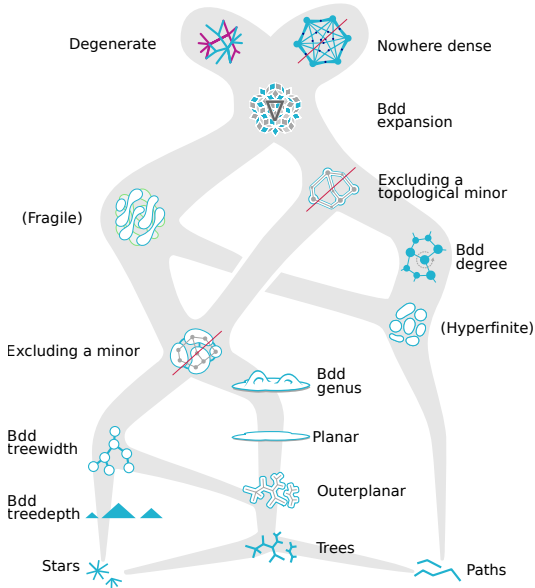
- non-degenerate \Rightarrow hard?
- high girth 3-regular \Rightarrow hard?
- contains expanders \Rightarrow hard?

Notions of sparsity



Theorem (RWŽ)
 $\bar{\mathcal{G}}$ is hyperfinite
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In group theory:

Corollary (Elek)

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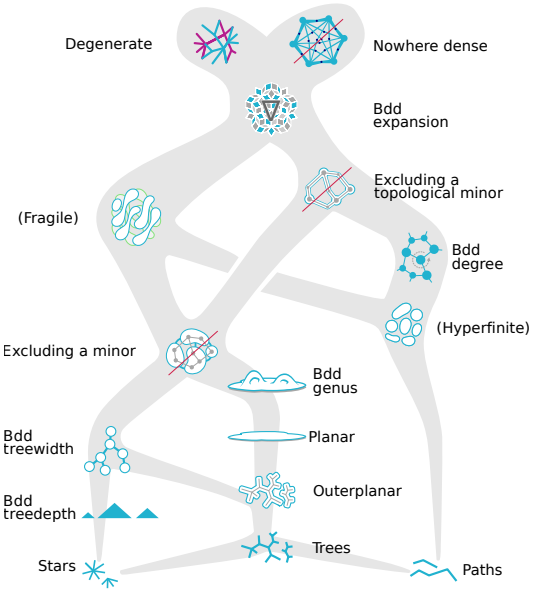
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Can results on property testing
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Thank you for listening!